A VALIDATION OF THE NCHRP 117/144
TRAFFIC NOISE LEVEL PREDICTOR MODEL
FOR LOW DENSITY, CLOSE DISTANCE
TRAFFIC ON I 696 BETWEEN I 75 AND I 94



TESTING AND RESEARCH DIVISION RESEARCH LABORATORY SECTION

A VALIDATION OF THE NCHRP 117/144 TRAFFIC NOISE LEVEL PREDICTOR MODEL FOR LOW DENSITY, CLOSE DISTANCE TRAFFIC ON I 696 BETWEEN I 75 AND I 94

G. H. Grove

Research Laboratory Section Testing and Research Division Research Project 73 TI-147 Research Report No. R-1075

Michigan State Highway Commission
Peter B. Fletcher, Chairman; Carl V. Pellonpaa,
Vice-Chairman; Hannes Meyers, Jr., Weston E. Vivian
John P. Woodford, Director
Lansing, November 1977

The information contained in this report was compiled exclusively for the use of the Michigan Department of State Highways and Transportation. Recommendations contained herein are based upon the research data obtained and the expertise of the researchers, and are not necessarily to be construed as Department policy. No material contained herein is to be reproduced—wholly or in part—without the expressed permission of the Engineer of Testing and Research.

ABSTRACT

The purpose of this study was to determine the applicability of the FHWA-approved NCHRP 117/144 traffic noise level prediction method to the special case of low density, low speed, and close distance traffic. The work was conducted in response to an immediate need to accurately determine future traffic noise levels at residences along the service drives of I 696 between I 75 and I 94, north of Detroit in the communities of Roseville, Warren, Centerline, and Madison Heights.

The study shows that a modified version of the NCHRP model is a valid traffic noise predictor if the descriptor used is L_{eq} (L equivalent) and it is calculated on the basis of traffic data which have been modified by transferring the 2D component of commercial traffic to the automobile-light truck category.

 L_{50} , L_{10} , and L_{eq} data from the presently used predictor and the proposed predictor are compared to measured data at five representative sites. Also, the report includes site photographs, tabulations of measured and predicted noise levels, and summarized statistical results.

Introduction

As a prerequisite for any proposed noise abatement treatment along the I 696 project between I 75 and I 94 in the Detroit Area, the Federal Highway Administration (FHWA) has requested the Department to validate the approved NCHRP 117/144 (1, 2) noise level predictor model for service drive conditions.

Because this model was developed for high volume freeway conditions, some doubt exists as to its applicability to service drives having low density traffic operating near adjacent residences. The FHWA has approved the use of two noise level descriptors, L_{10} and L_{eq} , in their Federal Noise Standard, FHPM 7-7-3, for traffic noise impact studies. The objective of this investigation is to determine if either of these two descriptors as they now exist in the computer program (3) is acceptable for the subject service drive noise level predictions. If not, then what modification is necessary to achieve acceptability.

In conjunction with this task, the present classification breakdown of automobiles and commercial vehicles is to be investigated as it pertains to the noise model.

Background

The NCHRP 117/144 noise level prediction model is based upon an empirically derived L₅₀ descriptor. The L₁₀ descriptor is calculated from the L₅₀ by a nonlinear adjustment factor, f(A), which is a function of the hourly vehicle volume, V, the average vehicle operating speed, S, and the equivalent lane distance, D_E, namely:

$$L_{10} (dbA) = L_{50} (dbA) + f(A)$$
 (1)

where the adjustment argument

$$A = V \frac{D_E}{S}$$
 (2)

(The adjustment factor appears as Figure B.10 in NCHRP 117 (1).)

An L_{10} noise level is calculated for automobiles and commercial vehicles separately and later logarithmically summed to obtain the total L_{10} .

The NCHRP 117/144 model only determines L_{50} and L_{10} noise levels. Thus, because we want to also predict energy equivalent noise levels, L_{eq} , the model was modified. By assuming that the noise levels (L_j ; j=0, $1,\ldots,99$) are normally distributed, it can be shown ($4,\underline{5},\underline{6}$) that the desired L_{eq} values can be calculated from the L_{50} and L_{10} noise levels as follows:

$$L_{eq} = L_{50} + 0.07 (L_{10} - L_{50})^2$$
 (3)

The above assumption of normally distributed noise levels holds for free flowing, dense traffic (7) such as that found traveling our high volume free-ways. The range of geometric and traffic parameters over which this assumption holds was given more precisely (6) in terms of the argument of the previously discussed adjustment factor as:

$$A > 200 \text{ ft} - \text{vehicles/mile}$$
 (4)

This Leq calculation, Eq. (3), has been a supplementary output of the Traffic Noise Level Predictor Computer Program (3) since 1974.

Because Eq. (3) is the only method of obtaining L_{eq} noise levels from the NCHRP 117/144 model, it was decided to investigate whether it was also acceptable for noise level predictions along the I 696 service drives, even though A < 200.

Scope

Because of the interdependencies of the predicted L_{50} , L_{10} , and L_{eq} noise levels, all three descriptors were selected for comparison with their respective measured values.

In selecting field measurement sites, an attempt was made to find flat, at-grade and reasonably unobstructed areas, with traffic volumes and speeds similar to those projected for the I 696 service drives during the design year. After surveying the I 696 project area, five sites along its completed service drives were chosen for field measurements. These sites (Appendix A) are:

- 1) Eastbound 11 Mile Rd, 500 ft west of Schoenherr (Fig. A1).
- 2) Eastbound 11 Mile Rd, between Grandmont and Roberta (Fig. A2).
- 3) Eastbound 11 Mile Rd, between Richard and Burg (Fig. A3).
- 4) Westbound 11 Mile Rd, between Lorraine and Richard (Fig. A4).
- 5) Westbound 11 Mile Rd, 300 ft west of El Capitain (Fig. A5).

At each of these sites, four measurement distances were selected, namely: 25, 50, 75, and 100 ft from the center of the near lane of traffic. Two model db 601 Metrosonics sound level analyzers, equipped with General Radio 1962-9601 microphones and 1972-9600 preamplifiers were used. The instruments, placed at two of the four measurement distances simultaneously sampled the noise levels over 15 minute periods at a rate of one sample per second. Due to the availability of only two simultaneous measurement channels, the 50 and 100 ft data were taken as one group while the 25 and 75 ft data were taken as another group. From these data, the L10, L50, and Leq were automatically computed by the instruments. A total of 25 data sets were taken at each of the four distances (Appendix B).

Vehicles were counted per individual MDSHT classification type during each sample period. Individual vehicle speeds were noted from dual pneumatic tubes spaced at a known distance along the roadway. Pressure switches connected to these tubes controlled a time-lapse counter to produce individual vehicle operating speeds. These detailed vehicle type and speed data were obtained to allow grouping of the various vehicle classifications into the two allowable traffic model parameters, i.e., hourly vehicle volume and percent commercial.

Our present definition of a commercial vehicle is given as: "A commercial vehicle is any motor vehicle having a gross vehicle weight greater than 10,000 lb, and buses having a capacity exceeding 15 passengers."

Data Analysis

In the following, the method of data analysis is described and the reason for its selection is explained. Three model-data variation cases were analyzed. These are:

- 1) existing prediction model with the existing definition of percent commercial,
- 2) existing prediction model with a modified definition of percent commercial, and,
- 3) modified prediction model with a modified definition of percent commercial.

Because of the method of noise level measurement and the interdependencies of certain noise levels, a multivariate analysis of variance method was selected as the most appropriate analysis method.

In this analysis, the hypothesis tested was whether or not two population mean vectors (a four-component vector for both measured and predicted data) are equal at the 0.050 significance level based on 25 dependent pairs of observation vectors. The L_{50} , L_{10} , and L_{eq} data were tested separately. The 95 percent simultaneous confidence intervals for linear compounds of mean differences will be illustrated later in this section.

First, using the present definition of a commercial vehicle, L_{50} , L_{10} , and L_{eq} noise levels were calculated with the present prediction model. This resulted in gross overpredictions for all sample periods at all sites with errors as large as 12.5 dbA. Due to the magnitude of the errors, no further analysis of this case was deemed necessary; the results were unacceptable.

Prior to making these noise level calculations, it was suspected that some of the previously defined commercial vehicles did not possess the same high noise emission levels attributed to heavy commercial vehicles. Specifically, vehicles having a two-wheel steering axle and a four-wheel drive axle, commonly referred to as type '2D' in the MDSHT vehicle classification system, were suspect. On the I 696 service drives, these type 2D vehicles comprise up to 50 percent of all vehicles presently considered as commercial. Due to the sensitivity of the prediction model to the percent commercial input parameter, it is extremely important that they be included in the appropriate category. Thus, the percent commercial figures were adjusted so as to shift the type 2D vehicles from the commercial to the automobile-light truck category.

The resulting predicted noise levels still erred on the high side in general, but to a lesser extent than previously. In order to ascertain whether or not the predicted noise levels were statistically acceptable, the previously discussed multivariate analysis of variance method was applied to the predicted and measured noise levels for each distance. Based upon a 95 percent confidence level, and the modified percent commercial definition, the $\rm L_{50}, \, L_{10}, \,$ and $\rm L_{eq}$ descriptors were not acceptable at all four distances. Thus, the present noise prediction program (3) is not an acceptable predictor for low density, close distance service drive traffic.

Next, an attempt was made to modify the present predictor or to derive a new predictor for the service drive applications under study. In reviewing NCHRP Report 117, it was noted that a special low density traffic flow effect was discussed but not included in the graphical method and therefore was not a part of the computer predictor program (3). When discussing this traffic flow model, the previously defined combination of terms, namely $A=V\,\frac{D_E}{S}$, is an important quantity to consider. There is an 'A' para-

meter for each of the two vehicle types in the prediction model. For sufficiently low density traffic flow (A < 1,320 ft - vehicles/mile), distance behavior of the mean noise level (L50) is dependent not only on the -4.5 db per distance doubling term (-15 log 10 DE), but also on the density term $(10 \log_{10} \tanh 1.19 (10^{-3}) A)$. For very low density flows (A < 420 ft vehicles/mile), the density term defined above, tends to the value 1.19 (10^{-3})A, which effectively reduces the total distance dependence of the mean noise level to -1.5 db per distance doubling ($-5 \log 10$ D_E). In the NCHRP 117 graphs and in the present prediction model, the equivalent lane distance, D_{E} , was fixed at 100 ft in the hyperbolic density term. Based upon this information a modified predictor program was created which allowed the equivalent lane distance to vary in the density term. Using this modified model and the modified definition of percent commercial (transfer type 2D) for the service drives, new L_{50} , L_{10} , and L_{eq} noise levels were calculated (Appendix B). By observation, only the L_{eq} plot appeared approximately centered about the ideal zero error line.

This data base was then analyzed per the same analysis of variance method used previously. This time, the Leq descriptor with a bias term of -0.8 dbA included in the predicted noise levels was acceptable at the 95 percent confidence level (Table 1). From Table 1, it should be noted that even though a negative bias applied to the predicted data produced an acceptable Leq predictor, the acceptable range of bias was rather narrow (i.e., -0.843 < ε_{eq} < -0.751). A bias of -0.8 dbA was chosen. The predicted L50 data will be acceptable for a bias in the range of -2.876 < ε_{50} < -1.932, while there is no bias which will allow the L10 to pass. A linear regression scatter plot (Fig. 1) of predicted vs. measured levels resulted in a correlation coefficient of 0.868.

TABLE 1
MULTIVARIATE ANALYSIS OF VARIANCE:
95 PERCENT SIMULTANEOUS CONFIDENCE
INTERVALS ON Leg MEAN DIFFERENCES

Distance, $\mathrm{D_N},$ ft	Lower Confidence Limit	Upper Confidence Limit
25	-0.043	+3.051
50	-0.064	+2.384
75	-3.057	+0.049
100	-1.586	+1.810

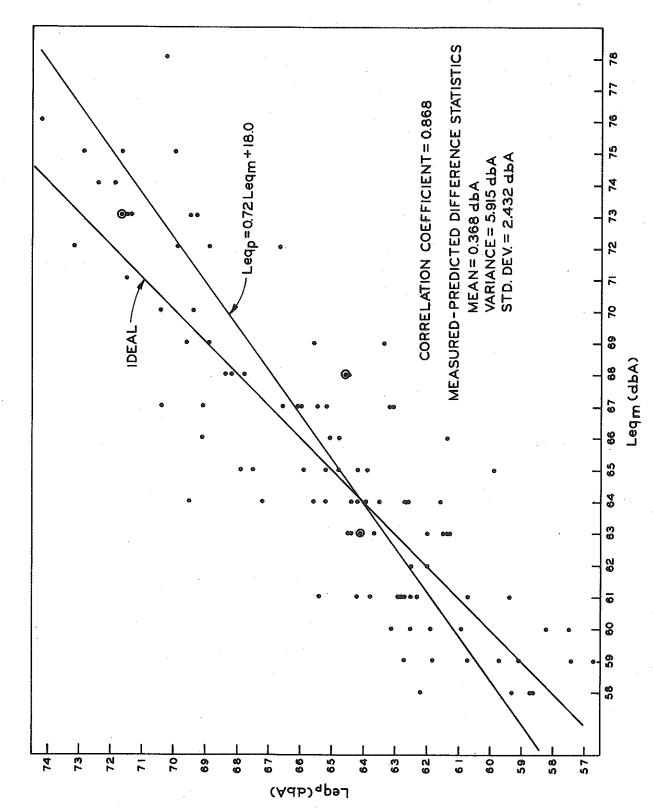


Figure 1. Predicted versus measured Leq (dbA) noise levels for I 696 low density, close distance service drive.

In summary, our proposed L_{eq} noise level predictor for the I 696 service drive conditions tends to underpredict by 0.368 dbA and has a variance and standard deviation of 5.915 dbA and 2.432 dbA, respectively.

Conclusions

Based upon the data taken at the five measurement sites, it appears that the present definition of percent commercial should be modified so as to shift the type 2D vehicles from the commercial category to the automobile and light truck classification. This modification is suggested only for service drives and other roadways having traffic flows similar to that found at the measurement sites.

Also, the present prediction program is not acceptable for predicting either $\rm L_{10}$ or $\rm L_{eq}$ traffic noise levels for conditions similar to those measured.

By modifying the present program so as to include a variable equivalent lane distance quantity in the mean noise level density term, and a bias term, an acceptable L_{eq} predictor has been found for traffic conditions similar to those measured. These traffic conditions cover a range from 430 to 1,650 total vehicles/hour with up to 7.8 percent commercial (modified definition), average automobile and light truck speeds from 30 to 38 mph and commercial vehicle speeds from 23 to 39 mph. Based upon FHPM 7-7-3, the I 696 1990 Design Year volume, percent commercial, commercial speed, and automobile-light truck speed ranged over 500 to 1,800 vehicles/hour, 0.6 to 3.3 percent commercial, 23 to 33 mph and 25 to 35 mph, respectively, for noise level analysis purposes. It can be concluded that the I 696 service drives having traffic flows within the above mentioned ranges can be analyzed by the modified model.

Because the L_{eq} descriptor has been found acceptable for certain low density traffic and the fact that the mainline traffic is a much better approximation of free flowing dense traffic, it is concluded that the original L_{eq} descriptor is acceptable for freeway noise level predictions. However, the definition of percent commercial for freeway traffic will remain unchanged until such evidence, if any, is presented to warrant a modification.

In summary the resultant noise levels will be the db sum of the $\rm L_{eq}$ levels from mainline traffic calculated in the usual manner, plus the $\rm L_{eq}$ levels from service road traffic calculated with the modified predictor model and with type 2D vehicles classified as automobile-light truck.

REFERENCES

- 1. Gordon, C. G., Galloway, W. J., Kugler, B. A., Nelson, D. L., "Highway Noise: A Design Guide for Highway Engineers," Transportation Research Board, NCHRP Report No. 117, 1971.
- 2. Kugler, B. A., Piersol, A. G., 'Highway Noise: A Field Evaluation of Traffic Noise Reduction Measures," Transportation Research Board, NCHRP Report 144, 1973.
- 3. Grove, G. H., "Traffic Noise Level Predictor Computer Program," Michigan Department of State Highways and Transportation, Research Report No. R-942, October 1974.
- 4. Delany, M. E., Copeland, W. C., Payne, R. C., "Propagation of Traffic Noise in Typical Urban Situations," National Physical Laboratory, Report Ac 54, October 1971.
- 5. Wesler, J. E., "Manual for Highway Noise Prediction," Transportation Systems Center, Report No. DOT-TSC-FHWA-72-1, March 1972.
- 6. Kugler, B. A., Commins, D. E., Galloway, W. J., "Highway Noise: A Design Guide for Prediction and Control," Transportation Research Board, NCHRP Report No. 174, 1976.
- 7. Nelson, P. M., "The Combination of Noise from Separate Time Varying Sources," Transport and Road Research Laboratory, Report LR 526, 1972.

$\label{eq:appendix} \textbf{APPENDIX A}$ $\label{eq:measurement site photographs}$

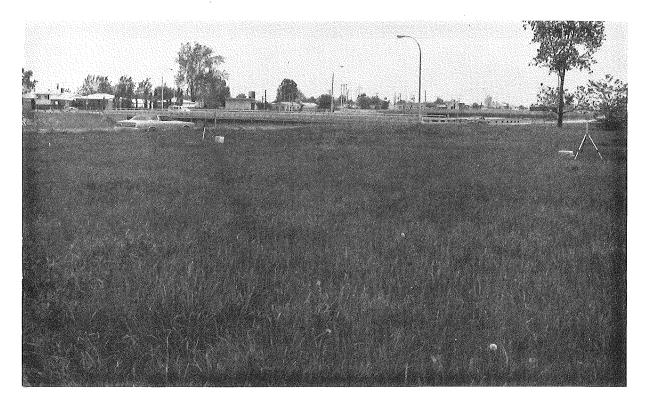


Figure A1. Site 1 - 11 Mile Road, eastbound, 500 ft west of Schoenherr.

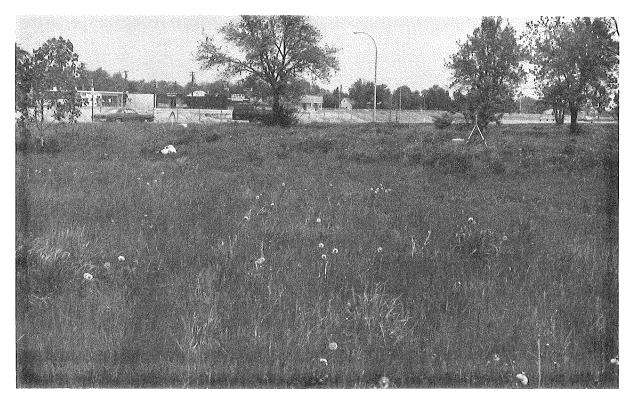


Figure A2. Site 2 - 11 Mile Road, eastbound, between Grandmont and Roberta.



Figure A3. Site 3 - 11 Mile Road, eastbound, between Richard and Burg.

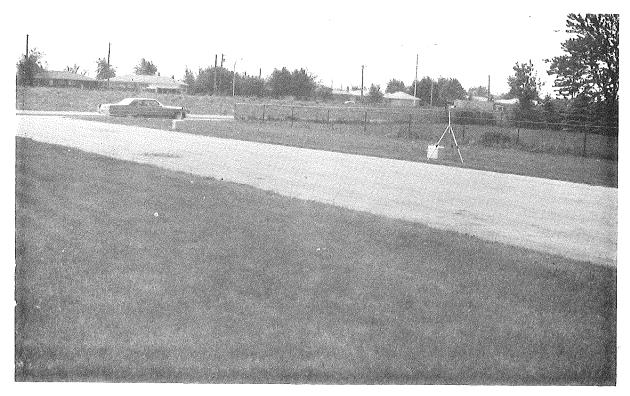


Figure A4. Site 4 - 11 Mile Road, westbound, between Lorraine and Richard.



Figure A5. Site 5 - 11 Mile Road, westbound, 300 ft west of El Capitain.

$\label{eq:appendix} \textbf{APPENDIX B}$ TRAFFIC VOLUMES, SPEEDS AND NOISE LEVELS

NCHRP 117/144 NOISE MODEL VALIDATION FOR LOW VOLUMES, LOW SPEEDS, AND CLOSE DISTANCES EASTBOUND 11 MILE RD, 500 ft WEST OF SCHOENHERR TABLE B1

(2-lane pavement)

								1		_		
1-942	ı, abA Jar	Leq	66.6	64.6 61.4	63.2 59.4	65.5	65.1 61.9	69.3	71.4	72.9 69.1	69.5 64.1	71.9 67.9
Modified R-942	zD as Car	L50	60.9	59.2 56.3	58.5 55.5	60.6 57.5	59.8 56.8	62.0	62.6 59.6	64.6 61.4	62.6 59.0	64.8 61.1
Mod	YOUR	$_{ m L_{10}}$	69.9 67.1	68.0 64.9	66.7 63.0	69.0	68.5 65.3	72.2	73.8	75.5 71.9	72.5 67.5	74.9 71.0
dbA	Car	Leq	69.4	67.2 62.1	65.5 60.1	68.0	67.7 62.5	73.9 65.2	76.8 68.9	78.4 70.8	74.0 65.5	77.1 69.6
	88	L50	62.8	61.2 57.0	60.4 56.2	62.4 58.2	61.7 57.5	66.1 59.8	67.4 61.0	69.1 62.7	66.6	68.7 62.3
Voise I	Ø	L10	72.5	70.5 65.5	68.9 63.6	71.4	70.9 65.9	76.7	79.0 71.6	80.6 73.4	76.9	79.7
licted 1	Truck	Leq	74.5 69.1	71.5 66.5	74.8	75.6 70.1	75.4 70.0	77.5	81.0 73.1	82.7 74.7	78.2 70.5	84.3 75.6
R-942 Predicted Noise Level,	as	L50	65.4	63.0 58.8	65.0	66.1 62.0	65.7 61.5	68.0	70.4 64.0	72.2 65.8	68.8 62.4	73.7
R-94	2D	Γ_{10}	76.8	74.0 69.3	76.8	77.8	77.5	79.6	82.7 75.4	84.4	80.4	86.0 78.2
Noise	dbA	Leg	67 61	68 63	67	67 61	99	73	73	75 66	73	74 65
Measured Noise	Level, o	L50	62 59	61 58	60 58	61 58	60 57	65 59	59	99	65 59	68
Meas	н	$_{ m L_{ m 10}}$. 70	69 64	69	69	69	76	76 65	77	76 66	22
	Distance, ft		50 100	50 100	50	50 100	50	25 75	25 75	25 75	25 75	75
9	1	SA	34.1	32,5	32.7	33.6	33.8	37.5	36.9	36.1	36.9	35.0
Average Vehicle Speeds, mph	2D as	ST S	29.9	27.7	31.0	31.0	26.6	32.5	33.4	31.2	30.1	32.7
verage Speeds	as	Truck	34.6	32.3	33.4	34.1	34.3	37.8	38.0	37.2	37.7	37.2
Ą	2D	ST	31.0	29.9	30.4	31.6	30.2	33.8	33.4	31.4	29.9	32.0
nt Commercial	4	Car	3.73	2.96	2.36	3.01	2.82	3.68	6.87	6.59	3.36	5.29
Percent Commerc Vehicles, TMIX	G.	Truck	7.45	5.93	9.45	8.43	9.15	7.35	12.2	11.4	6.71	12.7
Hourly Volume, Q	, d.	Car	644	540	508	664	568	544	524	899	596	756
Hourly V	ç	Truck	644	540	508	664	568	544	524	899	969	756
	Time		9:43 to 9:58 a.m.	10:01 to 10:16 a.m.	10:18 to 10:33 a.m.	10:35 to 10:50 a.m.	10:53 to 11:08 a.m.	9:39 to 9:54 a.m.	10:04 to 10:19 a.m.	10:23 to 10:38 a.m.	10:42 to 10:57 a.m.	11:02 to 11:17 a.m.
•			October 4, 1977 May 3, 1977 Otober 4, 1977 Otos mph Wind Speed Otos mph Wind Speed Clear Sky Clear Sky									

NCHRP 117/144 NOISE MODEL VALIDATION FOR LOW VOLUMES, LOW SPEEDS, AND CLOSE DISTANCES EASTBOUND 11 MILE RD BETWEEN GRANDMONT AND ROBERTA TABLE B2

Noise Level, dbA 2D as Car Modified R-942 58.2 55.1 L₅₀ 61.9 58.8 58.4 55.1 57.4 57,9 54.0 61.5 57.8 60.5 64.0 61.1 63.1 60.0 Γ_{10} 65.6 64.8 66.2 71.0 71.1 66.2 75.5 71.4 74.1 66.1 65.0 61.0 63.8 58.2 64.9 59.4 71.6 73.2 64.3 78.9 72.4 63.8 76.9 69.2 64.5 58.9 63.2 63.7 L_{eq} db. 2D as Car 59.2 60.0 58.9 65.3 58.9 64.9 58.6 68.9 62.5 65.6 59.2 67.7 60.0 55.8 60.4 56.2 R-942 Predicted Noise Level, L_{50} 68.3 62.9 75.8 75.4 67.3 79.1 71.9 6.09 67.2 74.7 65.4 80.8 68.0 62.4 67.3 61.6 L_{10} 79.9 72.6 67.6 69.9 79.8 L_{eq} 67.6 62.5 70.7 65.9 76.2 78.7 80.2 72.4 69.4 64.4 as Truck 69.7 63.6 59.4 60.5 56.3 62.0 61.9 67.2 68.3 61.9 69.8 63.5 69.7 62.0 57.8 $_{L50}$ 2D 80.5 81.7 74.5 72.6 78.5 82.0 74.8 81.8 74.6 72.3 75.0 73.1 $^{L_{10}}$ 70.6 Leg | Measured Noise Level, dbA 68 72 68 71 65 62 59 63 61 58 63 60 68 59 25 80 $_{L50}$ 57 56 57 55 55 57 56 50 58 57 60 57 60 57 58 710 65 64 65 64 60 64 59 64 60 70 71 72 77 71 (2-lane pavement) Distance, 25 25 50 25 25 25 75 20 50 50 50 Ħ 35.6 33.9 33.2 31.8 31.2 32.130.8 37.5 35.1 $\mathbf{S}\mathbf{A}$ 35. co co Car Average Vehicle Speeds, mph 2 23.5 28.8 24.3 31.0 29.0 29.6 31.0 35.1 39.4 ¢, ST댨 34.6 32.5 37.8 35.9 35.1 35.6 33.2 32.1 31.031.42D as Truck SA 34.6 29.2 31.6 27.7 29.0 37.5 30.9 29.6 30.7 33.0 ST Percent Commercial Vehicles, TMIX 2D as Car 3.45 2.72 1.52 92.0 0.86 1.610.74 7.80 6.34 1.83 2D as Truck 5.30 6.82 4.31 4.84 6.42 6.67 9.48 9.22 8.84 98.6 Ġ 2D as Car 496 540 464 564 588 568 528 528 464436 Hourly Volume, 2D as Truck 528 528 464 496 436 540 464 564 588 568 12:58 to 1:13 p.m. 12:10 to 12:25 p.m. 12:28 to 12:43 p.m. 1:29 p.m. 1:50 p.m. 2:07 p.m. 12:27 to 12:42 p.m. 1:34 p.m. 12:44 to 12:59 p.m. 1:02 to 1:17 p.m. Time 2 1:19 to 1:14 to 1:35 to 1:52 Сјевк Зк?. Clear Sky 0 to 9 mph Wind Speed 0 to 10 mby Mind Speed

61.5

62.7

62.6 58.2

 $\Gamma_{\rm eq}$

62.0 57.4

61.3

67.8

68.4 62.8

73.2

68.2 62.5

71.5

October 4 and 18, 1977

7791 ,8 (sIM

NCHRP 117/144 NOISE MODEL VALIDATION FOR LOW VOLUMES, LOW SPEEDS, AND CLOSE DISTANCES TABLE B3

Modified R~942 Noise Level, dbA 2D as Car 65.2 65.6 66.0 63.9 59.3 65.9 69.1 63.1 69.6 70.4 68.9 69.4 $_{150}$ 60.3 57.2 60. 7 57. 6 61.0 60.6 60.9 63.2 59.2 63.5 59.5 64.2 64.0 59.5 64.8 69.3 <u> 1</u>2 68.7 69.1 69.4 66.3 67.4 72.4 72.8 67.7 73.7 68.9 72.4 66.0 72.9 72.2 63.6 72.2 $\mathbf{L}_{\mathbf{eq}}$ 68.0 62.8 65.4 60.1 68.4 63.3 73.1 64.4 73.9 65.6 74.9 66.99 9.79 68.5 63.5 62.4 R-942 Predicted Noise Level, dbA 2D as Car 62.2 58.0 62.6 58.4 62.8 58.6 62.0 57.8 62.7 58.5 66.7 67.0 8.19 66.9 67.5 61.4 L_{50} 69.0 76.9 77.9 75.6 67.2 75.7 71.0 71.4 71.8 711.7 76.2 68.0 Γ_{10} 68.9 75.9 76.3 68.6 76.9 78.5 75.6 73.2 71.0 74.0 68.7 78.8 H eq EASTBOUND 11 MILE RD BETWEEN RICHARD AND BURG as Truck 66.5 62.3 68.6 62.2 64.5 60.3 63.7 59.5 65.363.0 58.8 68.7 69.6 63.2 69.4 63.1 68.1 L_{50} 20 81.0 73.8 79 5 80.9 73.9 76.4 72.2 79.0 71.6 78.6 75.7 73.1 7,0 Leq Measured Noise Level, dbA 65 59 64 58 64 58 65 59 60 69 70 61 69 70 67 61 \mathbf{L}_{50} 58 50 23 55 58 60 55 60 55 61 55 61 56 62 56 Γ_{10} 67 67 60 67 67 60 71 62 71 72 72 71 67 61 (2-lane pavement) Distance, 50 50 F00 200 20 50 25 75 25 75 25 75 25 75 25 Ħ 35.3 34,1 37.1 36.2 36.5 36.0 37.9 35 8 % 28 Average Vehicle Speeds, mph Ü 28.0 32.9 30.4 29.5 31.1 29.6 33.2 30.3 32.4 Ю $\mathbf{S}\mathbf{I}$ 28 36.5 37.9 36.5 ιc 37.9 35.I 36.1 34.3 34.1 34.6 $_{\rm SA}$ 36. 2D as Truck 33.0 33.2 32.3 32.6 30.3 34.2 34.7 32.129.9 32.3 S Percent Commercial Vehicles, TMIX ŝ Car 2.653,12 1.14 2.96 2.94 3.80 1.59 2.87 4.5 0.97 20 2D as Truck 6,35 7.28 5.00 5.43 3.41 7.32 6.32 8.88 4.71 3.88 Ġ ģ 2D as Car Hourly Volume, 756 604 640 969 704 929 680 736 676 824 2D as Truck 604 640 969704 676 656 680736 756 824 9:00 to 9:15 a.m. 9:32 a.m. 10:10 to 10:25 a.m. 11:03 to 11:18 a.m. 11:21 to 11:36 a.m. 11:38 to 11:53 a.m. 11:55 to 12:10 p.m. 12:12 to 12:27 p.m. 9:50 a.m. 9:53 to 10:08 a.m. Time 2 9;35 to 9:17 Cjest Sky Clear Sky May 11, 1977 0 to 2 mph Wind Speed beeds briw Agm e of a October 18, 1977

NCHRP 117/144 NOISE MODEL VALIDATION FOR LOW VOLUMES, LOW SPEEDS, AND CLOSE DISTANCES WESTBOUND 11 MILE RD BETWEEN LORRAINE AND RICHARD TABLE B4

(2-lane pavement)

Average Vehicle Speeds, mph Distance, Level, dbA Layel, dbA	A Percent Commercial Average Vehicle Vehicle Speeds, mph as 2D as Truck	Speeds, mph Distance, Level, dbA Lev	Speeds, mph Distance, Level, dbA Lruck ST SA SA	verage Vehicle Distance, as 2D as 2D as 2D as 2D as 2D as 31.0 Distance, as 2D as 31.0 The control of the	ds, mph	Distance, Level, dbA Level dbA	Distance, Resurved Noise Level, dbA Lacol, dbA Laco	Measured Noise Level, dbA Lavel, dbA Lavel, dbA 68 56 66 7 61 54 61 7 67 55 64 7 61 52 58 7 61 54 60 7			H 66 66 66		as Truck L ₅₀ I, 65.5 74 61.3 68 61.0 68 62.1 70	174.2 68.9 68.9 68.4 775.4 70.0	2D 2D 70.4 6 65.0 5 65.7 5 65.2 5 65.	, , , , , , , , , , , , , , , , , , ,	8 4 4 8 8 1 1 9 9 1 1 1 9 9 1 1 1 9 9 1 1 1 1	Noise Level, dbA 2D as Car L10	Modified K-942 toise Level, dbA 2D as Car Lio L50 Leq 8.4 60.9 64.8 4.3 57.6 60.7 7.0 60.6 63.5 11.9 56.9 58.6 18.4 61.1 64.8 18.4 61.1 64.8
12:18 to 12:33 p.m. 796 796 3.52 1.00 28.9 33.9 26.5 33.5 100 61	3.52 1.00 28.9 33.9 26.5 33.5 100	52 1.00 28.9 33.9 26.5 33.5 100	28.9 33.9 26.5 33.5 50	33.9 26.5 33.5 100	9 26.5 33.5 50	5 33.5 50	5 50		67	വാ	57 64 54 59	73.7 69.0	64.0 59.8	70.6	63.8	62.5 6 58.3 6	65.7	67.7 6	61.2 57.5
, 50 12:51 p.m. 796 796 3.52 0.50 30.0 34.2 23.8 33.7 100 6	3.52 0.50 30.0 34.2 23.8 33.7 100	52 0.50 30.0 34.2 23.8 33.7 100	30.0 34.2 23.8 33.7 100	34.2 23.8 33.7 50	2 23.8 33.7 50	33.7 50	50 100		9	68 5 61 5	58 65 56 59	73.5 68.8	64.0 59.8	70.3 65.5	63.0	62.4 6 58.2 5	65.1 59.8	67.4 6	61.2 63.9 57.4 59.1
1:23 to 1:38 p.m. 832 832 6.25 2.40 31.7 38.2 28.9 37.3 25	6.25 2.40 31.7 38.2 28.9 37.3	26 2.40 31.7 38.2 28.9 37.3	31.7 38.2 28.9 37.3	38.2 28.9 37.3	28.9 37.3	37.3		25 75		75 6	64 78 57 68	81.8	70.5	79.4 71.7	77.4	68.0 7	74.1 66.0	73.7 6	65.0 70. 60.7 64.
1:44 to 1:59 p.m. 780 780 6.67 2.56 32.6 38.8 32.6 37.3 75	6.67 2.56 32.6 38.8 32.6 37.3	67 2.56 32.6 38.8 32.6 37.3	56 32.6 38.8 32.6 37.3	38.8 32.6 37.3	32.6 37.3	37.3		25 75		75 6 65 5	63 72 57 63	81.6 74.4	70.3 63.9	79.3 71.6	68.9	67.6 7	73.7 65.4	73.3 (64.5 69.9 60.2 64.1
2:18 p.m. 976 976 9.02 5.74 32.1 36.5 31.9 36.2 25	9.02 5.74 32.1 36.5 31.9 36.2	02 5.74 32.1 36.5 31.9 36.2	32.1 36.5 31.9 36.2	36.5 31.9 36.2	5 31.9 36.2	36.2	81	25 75		76 6	67 76 60 67	85.4	73.4 67.0	83.4 75.1	82.2	71.0	79.8 72.1	77.3 (73.4 (67.2 74. 63.3 70.
2:37 p.m. 852 852 2.82 0.94 30.7 35.7 29.2 34.9 75	2.82 0.94 30.7 35.7 29.2 34.9	82 0.94 30.7 35.7 29.2 34.9	30.7 35.7 29.2 34.9	35.7 29.2 34.9	29.2 34.9	34.9	ø	25 75		75 6 65 5	64 72 58 63	77.5	68.0	74.4 66.4	75.0 66.4	67.0	71.4	72.4	64.6 68. 59:7 62.
2:55 p.m. 1068 1068 4.87 1.12 31.1 36.5 30.9 35.4 25	4.87 1.12 31.1 36.5 30.9 35.4	87 1.12 31.1 36.5 30.9 35.4	31.1 36.5 30.9 35.4	36.5 30.9 35.4	30.9 35.4	35.4		25 75		76 6 66 6	67 75 61 67	81.9	71.0	79.3	75.9	61.8	72.3 64.1	73.5	66.3 70.0 61.0 63.1

NCHRP 117/144 NOISE MODEL VALIDATION FOR LOW VOLUMES, LOW SPEEDS, AND CLOSE DISTANCES WESTBOUND 11 MILE RD, 300 ft WEST OF EL CAPITAIN (2-lane pavement) TABLE B5

			ge	втэхА 7	11 27, 11 6, 6 to lear Sky	t oj sjai	nĐ .		Speed		fotoO m 7 ot 0 [-ymnu2	
	Time		9:18 to 9:33 a.m.	9:36 to 9:51 a.m.	9:53 to 10:08 a.m.	10:11 to 10:26 a.m.	10:28 to 10:43 a.m.	3:30 to 3:45 p.m.	3:49 to 4:04 p.m.	4:08 to 4:23 p.m.	4:27 to 4:42 p.m.	4:45 to 5:00 p.m.
Hourly V		2D as Truck	892	744	. 752	724	. 784	. 1644	. 1452	1584	. 1644	1612
Hourly Volume, Q		2D as	892	744	752	724	784	1644	1452	1584	1644	1612
Percent Co	- Actual	2D as Truck	4.93	4.30	5.32	5.52	5.61	1.70	1.93	1,52	2.68	1.74
cent Commercial	VIIII ,	2D as Car	1.35	2.69	1.06	2.21	2,55	0.24	0.83	0.51	0.73	1.24
Av	, di	Truck ST S.	29.1	30.1	33.2	30.9	32.3	30.0	30.0	32.8	33.5	32.6
verage Vehic	as	ck SA	36.5	36.5	35.9	34.4	35.2	39.1	38.2	37.6	33.0	36.8
Average Vehicle	2D as	ST ST	26.5	27.1	30.3	29.1	30.3	27.7	28.9	27.7	33.7	32.6
d)	T	sA.	35.9	36.2	35.7	34.2	35.2	37.3	37.3	37.6	37.0	36.8
	Distance, ft	_ 	50	50 100	50	50 100	50 100	25 75	25 75	25 75	25	25 75
Meas	l S	$^{\rm L}_{10}$	70	70 66	65	70	70 66	75	75 65	75 64	76 65	75 65
Measured Noise	Level, dbA	L ₅₀	63	62 59	60 59	61 60	60	7.1 6.1	70 61	70 61	E &	70 61
oise	¥.	Leq	69	72 69	65	67	64	75 65	73 64	73	73 63	74 64
R-942	CD	170	76.8	74.4	75.2	7.07	71.1	79.4	79.2	78.3	80.4	78.7
R-942 Predicted Noise Level,	as Truck	L ₅₀ 1	66.2 7 62.0 6	64.5 7	64.8 7 60.6 6	64.8 7	65.3 7	71.3 7	64.4	64.3	71.0	70.7 64.4
oted No	¥	Leq	74.1 7	71.4 7 66.4 6	72.3 6 67.3 6	72.9 7	73.3 7 68.1 6	75.9 7	75.7 7 68.0 6	74.7 7	77.2 7	75.2 7
ise Le	ZΩ	L10	70.8 6	72.5 6	69.5 64.0 5	70.9 6 65.8 E	71.9 6	76.4 7 67.9 6	68.6	76.7	76.8 °	69.8
	as Car	L50	63.7 6	63.6 6 59.4 6	62.7 6 58.5 6	62.9	63.4 (59.2 (70.4	69.9	63.9	64.0	70.4
dbA		Leg	67.3 6	69.1 7 64.0 6	60.6	67.4 (68.4 63.3	72.9 °	65.3	73.2	73.2	74.0
Modified R-942	ZD ZD	L10]	69.2 6	66.9	63.2	65.1	66.2 8	67.1	67.6	67.4	67.6	75.5 68.6
Modified R-942	2D as Car	L50]	62.4 6 58.7 6	61.9 6	61.3 6	61.1 6	61.8 (58.5 (69.2	68.5	63.1	69.1 63.2	69.0
42	4	$_{ m red}$	65.6 61.4	66.7 63.4	64.5 59.9	65.2 61.6	66.1 62.7	71.7 64.2	71.5 64.4	71.7 64.4	71.7 64.5	71.9