$\hat{1}$ Transportation Analysis \& Research

## MICHIGAN'S STATEWIDE

## traffic forecasting model

 VOLUME I-K EFPECTIVE SPEED MODEL:A PUBLIC INTERACTION TOOL
JANUARY, 1974
STATEWIDE STUDIES


## MICHIGAN DEPARTMENT

## OF

## STATE HIGHWAYS AND TRANSPORTATION

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January 16, 1974

Mr. Sam F. Cryderman
Deputy Director
Bureau of Transportation Plamming
Dear Mr. Cryderman:
The Transportation Survey and Analysis Section is pleased to present a report entitled "Effective Speed Model: A Pubiic Interaction Tool". The report documents the construction and testing of a model which is able to relate the congestion on a highway link to the effective running speed on that link.

This model could be used to stimulate public involvement in the transportation planning process. It communicates a measure of driving convenience which is easily understood and readily appreciated by members of the general public: for the average person, perhaps the handiest yardstick of traffic flow is his own speedometer. In addition, the model may prove useful in a new capacity-restraint algorithm. This algorithm seeks to accurately simulate the way in which traffic actually diverts from a heavily-traveled route to less-congested ones.

The Effective Speed process was implemented by Terry L. Gotts and James E. Carroll of the Statewide Studies Unit, under the supervision of Richard E. Esch. The report was prepared by Mr. Gotts.

Sincerely,


Keith E. Bushnel1
Engineer of Transportation Survey and Analysis

# EFFECTIVE SPEED MODEL: A PUBLIC INTERACTION TOOL 

BY

TERRY L. GOTTS

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## PREFACE

An increase in community involvement in the rransportation planing process is an mportant goal behind much recent rederal legislation. One possible solution is to attempto explain what effect each of a number of alternative transportation pland would have on every road in the highway system. Would a road become less congested or more congested as a result of each plan? How would the peakmosur speed on the road be affected?

These and other similar questions are related to the "level of service" and "effective speed" on a road. If a transportation agency could ahow an interested taxpayer a sample picture of traffic and say, "This is what the peak-hour traffic on the highway you drive will look like, and the speed will ibe about 55 miles per hour", many communication problems would be resolved. The subsequent feedback from the community might also represent a significant contribution to the final choice of a transportation plan. A person who would dismiss talk of "AADT's" or "DHV's" as jargon might appreciate a discussion of something as down-toearth as is probable speedometer reading.

The question of degree of congestion is covered by Volume I-H in this series, entitled "Level of Service: A Public Interaction Application". This report deals with the second topic, that of expected effective driving speed.

This report is Volume $I m$ in the $S$ tatewide series. Previous reports in the series are:
 Mode 1

Volume $\quad I-H-\infty$ Level of Service Systems Analysis Model: A Public Interaction Application

Volume I $\quad$ Jom ServicemArea Model
Volume $I T$ Developnent of Network Models


Volume $V$ Part $A=-$ Travel Model Development: Reformation- Trip Data Bank Preparation
$V o l u m e \quad$ Part B- Development of the Statewide Sociom
$\quad$ Economic Data Bank for Trip Generation-Diso tribution

Volume , VI $=-\quad$ Corridor Location Dynamics
Volume VIII -- Design Hour Volume Model Development
Volume VIII-A - Capacity Adequacy Forecasting Model
Volume VIII- Statewide Public and Private Facility file
Volume $I X \rightarrow$ Statewide Socio-Economic Data File


## INTRODUCTION

Some researchers have recently begun investigating the functional relationshlp between runntig speed and the som called volumemto-capacity or ${ }^{11} V^{\prime \prime \prime}$ ratio. This ratio is defined as the design hour volume (DHV), or thirtieth-highest four occurm ring in a year, divided by the adjutted practical hourly capacity; all calculations are performed on a link-bymink basts. Scudies
 that as congestion on a route increases, the efective driving speed of that route drops. They try to provide answers to questions like "By how many miles per hour does the speed on this route drop with a $10 \%$ rise in traffic?" or "Suppose rush-hour traffic Is rexouted from this collectormdistributor to this freeway: would people's driving time be significantly affected?"

The effective speed model automates the process and expands it to the system level. After future traffic assignments on a number of alternative transportation plans, the model demonstrates how driving speeds on each segment of ruxal state trinkline would change as a result of changed travel patterns and resulting volumes. Hopefully, information such as this could be a viable means of promoting public involvement in the transportation planning process.

1
See, for example: Curry, D.A., and Anderson, D.G. Procedures for Estimating Highway User Costs, Alr Pollution, and Noise Effects. NHCRP Report 133, HBR, 1972 .

## METHOD OF ANALYSIS



## METHOD OF ANALYSIS

The Statewide Traffic. Forecasting Model predicts future traffic on each gubsection, or "1ink", of a highway network composed of all state trunklines and certain selected county roads. This network is shown graphically in the computer plot of Figure 1. Each Link belonging to state trunkifne is given a capacity from the Highway Sufficiency Master, a master file which is used to establish construction and maintenance priorities. A future Design Hour Volume ("DHV") is then for forecast for each rural link; 2 and the quotient of the future DHV to the hourly capacity becomes the predicted V/C ratio for that 11nk。

Three separate sets of "curves" relating speed to $V / C$ ratio axe used. These curves are slightlymodified piecewisem linear approximations to those developed by Curry and Anderson. These curves are shown in Figures 2, 3 and 4 . The actual choice of the function to be used on a given link is determined first by the type of road - freeway two-lane or multi-1ane nonm freeway - and secondarily by number of lanes (for freeways) or percent of length having at least 1500 feet sight distance (for twomlane roads). All speeds are for passenger cars only. Once the curve to be used has been determined, the effective speed is simply the $Y$-coordinate on that curve which corresponds to the value of $V / C$. For example, suppose a link of four-lane freeway has a $V / C$ ratio of 0.4 . Referring to the bottom curve

2
See Statewide Transportation Analysis and Research Volume VII. Design Hour Volume Model Development. Michigan Department of State Highways, November; 1972.


FIGURE 2: FREEWAYS

$\because-6$ -

FIGURE 3 : MULTI - LANE NON-FREEWAYS


FIGURE 4: TWO - LANE ROADS

in Figure 2, it can easily be seen that the effective speed would be 55 miles per hour. Following the "0.4" vertical line to the " $8-1$ ane" curve, one sees that a $V / C$ ratio of 0.4 results in an effective speed of 57 miles per hour on an 8-1ane freemay.

As another example, refer to figure 4, the family of curves pertaining to two-lane roads. Suppose that a $2-1$ ane 1 ink has $V / C=0.4$. If drivers have only $20 \%$ of that link 1 wheh they can see 1500 feet ahead - - that is, passing maneuvers can be executed safely on only $20 \%$ of the link - - the average speed is about 44 mph . But on a similar link where drivers can see 1500 feet ahead for $80 \%$ of the length of the link, the average effective speed is 47 mph . This is logical, since a greater opportunity to pass means that faster vehicles are held back by slow vehicles less frequently, and therefore average speed rises.

The computerized model behaves exactly like a person consulting a set of curves, except that the "curves" are piecewise linear functions. That is, each of the curves in figures 2, 3 , and 4 are represented internally as a sequence of points along the curve joined by short straight line segments.


## TEST CASE

As an example of the output of the model, a test case was selected which is actually an alternative plan buing congidered f in a current corridor-selection process. The highway plan is shown graphically in Figure 5. The proposed additions to the existing system are indicated as heavy, dashed lines. Eoch new roads are two-lane roads, but they offer the advantage of not passing directly through any towns. Therefore, the feidatuely shorter travel time will tend to draw a good share of traffic off existing routes, making some of the existing routes more free-flowing.

The model results are shown in Figure 6 , with traffic being forecasted for year 2000. Speeds are in tenths of a mile per hour. The "boxed-in" region is magnified in Figure 7. The existing assigned speed is shown below each link, and the new effective speed is displayed above the link. For example, look at old US-31 (in the middle of the right half of the Figure); although the assigned speed was 50.0 ("500"), m.p.h.. the effective speed after the traffic assignment is $40.8 \mathrm{~m} \cdot \mathrm{p} . \mathrm{h}$. Note also that the forecasted effective speed on some sections of M-22 are actually higher than the assigned speeds, as a result of changing travel patterns.

Finally, Figures 6 and 7 contain two classes of links which are exceptional. One group consists of the county roads, shown as dashed lines. The other group is made up of centroid links, the imaginary connectors from the centroid (or center of population)


## FIGURE 6: COMPARISON OF ASSIGNED AND PROJECTED SPEEDS



FIGURE 7: SUMMARY REGION BLOW-UP

of a craffic forecasting zone to the hlghway network. These are shown as solid lines and have both old and new speeds equal to 35 m.p.h. in most cases, they are easily seen becanse one end is obviously not connected to the road aystem. Capactites are not expressed for these two classes of links and therefore $V / C$ ratios cannot be calculated for them. For that reason the model leaves speeds on centroid links and county roads anchanged.

One final remark: although in this test example speda have been allowed to fncrease as well as decrease that vergion of the model will probably not be used in many departmental applications. In most cases, the speed assigned to a link reflects more than just a V/C ratio; it will also be a product of the percent of commercial traffic, alignment, sight restriction lane width, surface conm dition, and many other link-specific factors. Therefore, the assigned speed on a link may, well be the highest average speed which can reasonably be expected there. In this case, it would be illogical to permit the model to estimate a higher effective speed than has already been assigned; thus speeds will be allowed only to decrease in response to. increasing levels of congestion.


## FUTURE MODIFICATIONS

In the near future the effective speed model will be used In confunction with the Stetewide Traffic Forecagting Model to provide a means of capacitymrestraint traffic assignmert. In an "alloor-nothing".assignment process maning that all eraffic bew tween two zones is loaded on the single minimumotime path foining them - - this method of capacity restraint could result in an unw realistic traffic assignment by diverting a majority of the original traffic off the overloaded routes.

The Statewide capacity-restraint method uses a "partial-1oad algorithm". After trees are built and a trip-table created, one quarter of the trips are loaded. A partial future DHV volume is created for each link by calculating $D H V=(0,25) X$ (future $A A D t$ ) X (future DHV percent), and this value is compared with the hourly adjusted practical capacity for the link to yield a V/C ratio. From this set of values new effective speeds are generated new trees are built, and another $25 \%$ of the trips are loaded on the new trees and added to the volume from the first load. At this point, half the trips have been loaded; the partial volumes on each link are again compared with the link capacity and new speeds are generated by this criterion. This simulates reality, because as a route begins to fill up, traffic is diverted onto parallel routes. The process is repeated twice more, until all trips have been loaded. The sequence of operations is shown graphically in Figure 8.

FIGURE 8: DIAGRAM OF'PARTIAL-LOAD PROCESS



## CONCLUSION


#### Abstract

In an effort to stimulate public involvement in whe transo portation planning process, the effective speed model was dew veloped to predict future driving speeds as a rewult of obanging travel patterns. A citizen who would be apathetic to a discussion of $A A D T{ }^{\prime} s$ and $D H V^{\prime} s$ as a result of a proposed transpotedtion plan might respond more constructively if he could be shown the effect of the new plan on his driving environment and the eatest teasure of traffic flow for the average person to understand is that given by his own speedometer. Moreover, the model can be used in a capacity-restraint algorithm. which may prove more logical than conventional methods. It has the potential to accurately simulate reality by diverting traffic as a route begins to fill wp with traffic.

The Statewide Studies Unit hopes that this report may serve as a springboard to further discussion and investigation of possible applications or modifications. Any comments or questions should be directed to Mr. Richard E. Esch, Supervisor, Statewide Studies Unit, Bureau of Transportation Planning. He may be reached by telephone at (517)373-2663.


